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Totally umbilical Hemi-slant submanifolds of Cosymplectic manifolds

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Abstract

In the present paper we have study totally umbilical hemi-slant submanifolds of Cosymplectic manifolds via Riemannian curvature tensor and finally obtained a classification for the Totally umbilical hemi-slant submanifolds of Cosymplectic manifolds.

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1 Introduction

The study of slant submanifolds was initiated by B. Y. Chen [3]. Since then many research articles have been appeared in this field, slant submanifolds are the natural generalization of both holomorphic and totally real submanifolds. A. Lotta [2] defined and studied these submanifolds in the setting of contact manifolds. Later on, J. L. Caberizo et al. [6, 7] studied slant, semi-slant and bi-slant submanifolds in contact geometry . In particular, totally umbilical proper slant submanifolds of Kaehler manifolds has been studied in [5].

The idea of hemi-slant submanifolds was introduced by A. Carriazo as a particular class of bi-slant submanifolds and he called them anti-slant submanifold after that, V.A. Khan and M. A. Khan [10] named these submanifolds Pseudo-slant submanifolds and studied them in the setting of Sasakian manifold. Recently, these submanifolds studied by B. Sahin for their warped product [6]. In this paper we will study hemi-slant submanifolds of Cosymplectic manifolds.

2 Preliminary Notes

A 2n + 1-dimensional C^{∞} -manifold \overline{M} is called A 2n + 1 dimensional C^{∞} manifold \overline{M} is said to have an almost contact structure if there exist on M a tensor field ϕ of type (1, 1), a vector field ξ and 1-form η satisfying.

$$\phi^2 = -I + \eta \otimes \xi, \ \phi(\xi) = 0, \ \eta \circ \phi = 0, \ \eta(\xi) = 1.$$
 (1)

There always exists a Riemannian metric g on an almost contact manifold M satisfying following conditions

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \ \eta(X) = g(X, \xi)$$
 (2)

where X, Y are vector fields on \overline{M} .

An almost contact structure (ϕ, ξ, η) is said to be normal if the almost complex structure J on the product manifold $\overline{M} \times R$ given by

$$J(X, f\frac{d}{dt}) = (\phi X - f\xi, \eta(X)\frac{d}{dt})$$

where f is the C^{∞} -function on $\overline{M} \times R$. The condition for normality in terms of ϕ, ξ and η is $[\phi, \phi] + 2d\eta \otimes \xi = 0$ on \overline{M} , where $[\phi, \phi]$ is the Nijenhuis tensor of ϕ . Finally the fundamental 2-form Φ is defined by $\Phi(X, Y) = g(X, \phi Y)$.

An almost contact metric structure (ϕ, ξ, η, g) is said to be cosymplectic, if it is normal and both Φ and η are closed, and structure equation of cosymplectic manifold is given by

$$(\bar{\nabla}_X \phi) Y = 0 \tag{3}$$

for any $X, Y \in T\overline{M}$, where $T\overline{M}$ is the tangent bundle of \overline{M} and $\overline{\nabla}$ denotes the Riemannian connection of the metric g. Moreover for cosymplectic manifold

$$\bar{\nabla}_X \xi = 0. \tag{4}$$

Let M be a submanifold of an almost contact metric manifold \overline{M} with induced metric g and if ∇ and ∇^{\perp} are the induced connection on the tangent bundle TM and the normal bundle $T^{\perp}M$ of M, respectively then Gauss and Weingarten formulae are given by

$$\nabla_X Y = \nabla_X Y + h(X, Y) \tag{5}$$

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$$\bar{\nabla}_X V = -A_V X + \nabla_X^\perp V \tag{6}$$

for each $X, Y \in TM$ and $V \in T^{\perp}M$, where h and A_N are the second fundamental form and the shape operator respectively for the immersion of M into \overline{M} and they are related as

$$g(h(X,Y),N) = g(A_N X,Y),$$
(7)

where g denotes the Riemannian metric on \overline{M} as well as on M.

For any $X \in TM$, we write

$$\phi X = TX + FX,\tag{8}$$

where TX is the tangential component and FX is the normal component of ϕX .

Similarly, for any $V \in T^{\perp}M$, we write

$$\phi V = tV + fV,\tag{9}$$

where tV is the tangential component and fV is the normal component of ϕV . The covariant derivatives of the tensor field T and F are defined as

$$(\bar{\nabla}_X T)Y = \nabla_X TY - T\nabla_X Y \tag{10}$$

$$(\bar{\nabla}_X F)Y = \nabla_X^{\perp} FY - F\nabla_X Y \tag{11}$$

From equations (3)(5), (6), (8) and (9) we have

$$(\bar{\nabla}_X T)Y = A_{FY}X + th(X,Y) \tag{12}$$

$$(\bar{\nabla}_X F)Y = fh(X, Y) - h(X, TY).$$
(13)

The mean curvature vector H on M is given by

$$H = \frac{1}{n} \sum_{i=1}^{n} h(e_i, e_j)$$

where n is the dimension of M and $\{e_1, e_2, \dots e_n\}$ is the local orthonormal frame of vector fields on M.

A submanifold M of Riemannian manifold \bar{M} is said to be totally umbilical if

$$h(X,Y) = g(X,Y)H \tag{14}$$

If h(X, Y) = 0 for any $X, Y \in TM$ then M is said to be totally geodesic. If H = 0, then it is said to be minimal.

A submanifold M of an almost contact metric manifold \overline{M} is said to be slant submanifold if for any $x \in M$ and $X \in T_x M$ is constant. The constant angle $\theta \in [0, \pi/2]$ is then called slant angle of M in \overline{M} . If $\theta = 0$ the submanifold is invariant submanifold, if $\theta = \pi/2$ then it is anti-invariant submanifold if $\theta \neq 0, \pi/2$ then it is proper slant submanifold.

For slant submanifolds of contact manifolds J. L. Cabrerizo et al. [6] proved the following Lemma

Lemma 2.1 Let M be a submanifold of an almost contact manifold M, such that $\xi \in TM$ then M is slant submanifold if and only if there exist a constant $\lambda \in [0, 1]$ such that

$$T^2 = \lambda (I - \eta \otimes \xi). \tag{15}$$

Thus, one has the following consequences of above formulae

$$g(TX, TY) = \cos^2 \theta[g(X, Y) - \eta(X)\eta(Y)]$$
$$g(FX, FY) = \sin^2 \theta[g(X, Y) - \eta(X)\eta(Y)]$$

Definition 2.2 A submanifold M of \overline{M} is said to be hemi-slant submanifold of an almost contact manifold \overline{M} if there exist two orthogonal complementary distribution D_1 and D_2 on M such that

- (i) $TM = D_1 \oplus D_2 \oplus \langle \xi \rangle$.
- (ii) The distribution D_1 is anti-invariant i.e., $\phi D_1 \subseteq T^{\perp} M$.
- (iii) The distribution D_2 is slant with slant angle $\theta \neq \pi/2$.

If μ is invariant subspace under ϕ of the normal bundle $T^{\perp}M$, then in the case of hemi-slant submanifold, the normal bundle $T^{\perp}M$ can be decomposed as

$$T^{\perp}M = \mu \oplus \phi D^{\perp} \oplus FD_{\theta}.$$

The Riemannian curvature tensor is defined as

$$\bar{R}(X,Y)Z = \bar{\nabla}_X \bar{\nabla}_Y Z - \bar{\nabla}_Y \bar{\nabla}_X Z - \bar{\nabla}_{[X,Y]} Z$$
(16)

The equation of Coddazi for totally umbilical hemi-slant submanifold M is given by

$$\bar{R}(X,Y,Z,V) = g(Y,Z)g(\nabla_X^{\perp}H,V) - g(X,Z)g(\nabla_Y^{\perp}H,V)$$
(17)

where $\overline{R}(X, Y, Z, V) = g(\overline{R}(X, Y)Z, V)$ and X, Y, Z are vector fields on M and $V \in T^{\perp}M$.

It is easy to see that Riemannian curvature tensor for Cosymplectic manifold satisfies the following properties

(a)
$$\overline{R}(\phi X, \phi Y)Z = \overline{R}(X, Y)Z$$
 (b) $\phi \overline{R}(X, Y)Z = \overline{R}(X, Y)\phi Z.$ (18)

By an extrinsic sphere we mean a submanifold of an arbitrary Riemannian manifold which is totally umbilical and has a nonzero parallel mean curvature vector [9].

3 Main Results

In this section, we will study a special class of hemi-slant submanifolds which are totally umbilical. Throughout the section we consider M as a totally umbilical hemi-slant submanifold of a Cosymplectic manifold. Now we have the following theorem

Theorem 3.1 Let M be a totally umbilical hemi-slant submanifold of a Cosymplectic manifold \overline{M} such that the mean curvature vector $H \in \mu$. Then one of the following statement is true

- (i) M is totally geodesic.
- (ii) M is semi-invariant submanifold.

Proof. For $V \in \phi D^{\perp}$ and $X \in D_{\theta}$, we have

$$\bar{\nabla}_X \phi V = \phi \bar{\nabla}_X V \tag{19}$$

using equations (5),(6) and (15) the above equation becomes

$$\nabla_X \phi V + g(X, \phi V) H = -\phi X g(X, V) + \phi \nabla_X^{\perp} V.$$

Then by orthogonality of two distributions and the assumption $H \in \mu$ the above equation takes the form

$$\nabla_X \phi V = \phi \nabla_X^\perp V \tag{20}$$

which implies that $\nabla_X^{\perp} V \in \phi D^{\perp}$, for any $V \in \phi D^{\perp}$. Also we have g(V, H) = 0, for $V \in FD^{\perp}$, then using this fact we derive

$$g(\nabla_X^{\perp}V, H) = -g(V, \nabla_X^{\perp}H) = 0.$$
(21)

The above equation implies

$$\nabla_X^{\perp} H \in \mu \oplus FD_{\theta}.$$

Now, for any $X \in D_{\theta}$, we have

$$\bar{\nabla}_X \phi H = \phi \bar{\nabla}_X H,$$

using equation (15), we obtain

$$A_{\phi H}X + \nabla_X^{\perp}\phi H = -\phi A_H X + \phi \nabla_X^{\perp} H.$$

Now, using the assumption, that M is totally umbilical the above equation takes the form

 $-Xg(H,\phi H) + \nabla_X^{\perp}\phi H = -\phi Xg(H,H) + \phi \nabla_X^{\perp} H,$

using the equation (4) above equation takes the form

$$\nabla_X^{\perp}\phi H = -TXg(H,H) - FXg(H,H) + \phi \nabla_X^{\perp} H,$$

taking Inner product with $FX \in FD_{\theta}$ and using the equation (15)

$$g(\nabla_X \phi H, FX) = -\sin^2 \theta \|H\|^2 \|X\|^2 + g(\phi \nabla_X^{\perp} H, FX).$$

Then from equation (15), the last term of right hand side is identically zero, thus the above equation becomes

$$g(\nabla_X \phi H, FX) + \sin^2 \theta \|H\|^2 \|X\|^2 = 0.$$
(22)

Since equation (22) has a solution if either $H \neq 0$, then $D_{\theta} = \{0\}$ i.e., M is totally real submanifold and if $D_{\theta} \neq \{0\}$ then M is totally geodesic submanifold or M is semi-invariant submanifold.

Now for any $Z \in D^{\perp}$, by equation (12)

$$-T\nabla_Z Z = A_{\phi Z} Z + th(Z, Z).$$

Taking Inner product with $W \in D^{\perp}$ the above equation takes the form

$$-g(T\nabla_Z Z, W) = g(A_{FZ}Z, W) + g(th(Z, Z), W).$$

As M is totally umbilical hemi-slant submanifold, then above equation becomes

$$g(Z,W)g(H,FZ) + g(tH,W)||Z||^2 = 0.$$
(23)

The above equation has a solution if either $H \in \mu$ or dim $D^{\perp} = 1$.

If moreover, $H \notin \mu$ then

Theorem 3.2 Let M be a totally umbilical hemi-slant submanifold of a Cosymplectic manifold \overline{M} such that dimension of slant distribution $D_{\theta} \geq 4$ and F is parallel, then M is either

(i) extrinsic sphere.

(ii) or anti-invariant submanifold.

Proof. Since dimension of slant distribution $D_{\theta} \ge 4$, then we can choose a set of orthogonal vectors $X, Y \in D_{\theta}$, such that g(X, Y) = 0. Now from equation (18)(b), we have

$$\phi R(X,Y)Z = R(X,Y)\phi Z$$

for any $X, Y, Z \in D_{\theta}$. Replacing Z by TY, we obtain

$$\phi \bar{R}(X,Y)TY = \bar{R}(X,Y)\phi TY.$$

Using equations (8) and (1), the above equation takes the form

$$\phi \bar{R}(X,Y)TY = -\cos^2\theta \bar{R}(X,Y)Y + \bar{R}(X,Y)FTY.$$
(24)

On the other hand, since F is parallel, then we have

$$\bar{R}(X,Y)FTY = F\bar{R}(X,Y)TY.$$
(25)

Then by equations (24) and (25) we have

$$\phi \bar{R}(X,Y)TY = -\cos^2\theta \bar{R}(X,Y)Y + F\bar{R}(X,Y)TY.$$
(26)

Taking Inner product in equation (26) by $N \in T^{\perp}M$, we get

$$g(\phi\bar{R}(X,Y)TY,N) = -\cos^2\theta g(\bar{R}(X,Y)Y,N) + g(F\bar{R}(X,Y)TY,N),$$

using equation (8) the above equation reduced to

$$\cos^2\theta g(\bar{R}(X,Y,Y,N) = 0.$$
⁽²⁷⁾

Then, from equation (17), we derive

$$\cos^2\theta g(Y,Y)g(\nabla_X^{\perp}H,N) - g(X,Y)g(\nabla_Y^{\perp}H,N) = 0.$$

Since X and Y are orthogonal vectors, then the above equation gives

$$\cos^{2}\theta g(\nabla_{X}^{\perp}H, N) \|Y\|^{2} = 0.$$
(28)

The equation (28) has a solution either $\theta = \pi/2$ i.e., M is anti-invariant or $\nabla_X^{\perp} H = 0 \ \forall X \in D_{\theta}$. By similar calculation for any $X \in D^{\perp} \oplus \langle \xi \rangle$ we can obtain $\nabla_X^{\perp} H = 0$, hence $\nabla_X^{\perp} H = 0$ for all $X \in TM$ i.e., the mean curvature vector H is parallel to submanifold, i.e., M is extrinsic sphere.

Now we are in position to prove our main theorem

Theorem 3.3 Let M be a totally umbilical hemi-slant submanifold of a Cosymplectic manifold \overline{M} . Then M is either

- (i) Totally geodesic,
- (ii) or Semi-invariant,
- (iii) or dim $D^{\perp} = 1$,
- (iv) or Extrinsic sphere.

case (iv) holds if F is parallel and dim $M \ge 5(odd)$

Proof. If $H \in \mu$ then by Theorem 3.1 M is either totally geodesic or semiinvariant submanifolds which are case (i) and (ii). If $H \notin \mu$, then equation (24) has a solution if dim $D^{\perp} = 1$ which is case (iii) and moreover if $H \notin \mu$ and F is parallel on M then by Theorem 3.2 M is extrinsic sphere which proves the theorem completely.

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