

Classification of 3-Lie bialgebras of type (L_b, C_b)

BAI Ruipu

College of Mathematics and Information Science,
Hebei University, Baoding, 071002, China
email: bairuipu@hbu.edu.cn

ZHANG Yan

College of Mathematics and Information Science,
Hebei University, Baoding, 071002, China
email: zhycn0913@163.com

Abstract

The 4-dimensional 3-Lie coalgebras with one-dimensional derived algebra, and 4-dimensional 3-Lie bialgebras of type (L_b, C_b) are classified. It is proved that there exist two classes 4-dimensional 3-Lie coalgebras with one-dimensional derived algebra which are (L, C_{b_1}) and (L, C_{b_2}) (Theorem 3.2), and seven classes of 4-dimensional 3-Lie bialgebras of type (L_b, C_b) (Theorem 3.3).

2010 Mathematics Subject Classification: 17B05 17D30

Keywords: 3-Lie algebra, 3-Lie coalgebra, 3-Lie bialgebra.

1 Introduction

Lie coalgebras and Lie bialgebras (cf [1, 2, 3]) are important in Lie algebras, and it has been playing an important role in mathematics and physics. Motivated by this, authors in paper [4] studied 3-Lie coalgebras and 3-Lie bialgebras. In this paper, we give the classification of 4-dimensional 3-Lie coalgebras with one-dimensional derived algebra, and then classify 4-dimensional 3-Lie bialgebras of type (L_b, C_b) . In the following, we suppose that F is a field of characteristic zero, and the zero multiplication of basis vectors in the multiplication table of 3-Lie algebras and 3-Lie coalgebras are omitted.

2 Preliminaries

A 3-Lie algebra [5] is a vector space L endowed with a linear multiplication $\mu : L^{\wedge 3} \rightarrow L$ such that for all $x, y, z, u, v \in L$,

$$\mu(u, v, \mu(x, y, z)) = \mu(x, y, \mu(u, v, z)) + \mu(y, z, \mu(u, v, x)) + \mu(z, x, \mu(u, v, y)).$$

3-Lie algebras can be described as follows. A 3-Lie algebra (L, μ) is a vector space L endowed with a 3-ary linear multiplication $\mu : L \otimes L \otimes L \rightarrow L$ satisfying $\mu(1 - \tau) = 0$, $\mu(1 \otimes 1 \otimes \mu)(1 - \omega_1 - \omega_2 - \omega_3) = 0$, where $\tau : L \otimes L \otimes L \rightarrow L \otimes L \otimes L$, $\tau(x_1 \otimes x_2 \otimes x_3) = \text{sign}(\sigma)x_{\sigma(1)} \otimes x_{\sigma(2)} \otimes x_{\sigma(3)}$, $\sigma \in S_3$, $\forall x_1, x_2, x_3 \in L$.

Define $\omega_i, 1 : L \otimes L \otimes L \otimes L \otimes L \rightarrow L \otimes L \otimes L \otimes L \otimes L$, $1 \leq i \leq 3$, by

$$1(x_1 \otimes x_2 \otimes x_3 \otimes x_4 \otimes x_5) = x_1 \otimes x_2 \otimes x_3 \otimes x_4 \otimes x_5,$$

$$\omega_1(x_1 \otimes x_2 \otimes x_3 \otimes x_4 \otimes x_5) = x_3 \otimes x_4 \otimes x_1 \otimes x_2 \otimes x_5, \quad (1)$$

$$\omega_2(x_1 \otimes x_2 \otimes x_3 \otimes x_4 \otimes x_5) = x_4 \otimes x_5 \otimes x_1 \otimes x_2 \otimes x_3, \quad (2)$$

$$\omega_3(x_1 \otimes x_2 \otimes x_3 \otimes x_4 \otimes x_5) = x_5 \otimes x_3 \otimes x_1 \otimes x_2 \otimes x_4. \quad (3)$$

Let (L, μ) be a 3-Lie algebra, L^* be the dual space of L . The dual map $\mu^* : L^* \rightarrow L^* \otimes L^* \otimes L^*$ of μ , satisfies $\forall x, y, z \in L$ and $\xi, \eta, \zeta \in L^*$, $\langle \mu^*(\xi), x \otimes y \otimes z \rangle = \langle \xi, \mu(x, y, z) \rangle$, and $\langle \xi \otimes \eta \otimes \zeta, x \otimes y \otimes z \rangle = \langle \xi, x \rangle \langle \eta, y \rangle \langle \zeta, z \rangle$, where $\langle \cdot, \cdot \rangle$ is the natural nondegenerate symmetric bilinear form on $L \oplus L^*$ defined by $\langle \xi, x \rangle = \xi(x)$, $\xi \in L^*$, $x \in L$. Then $\text{Im}(\mu^*) \subseteq L^* \wedge L^* \wedge L^*$, and $(1 - \omega_1 - \omega_2 - \omega_3)(1 \otimes 1 \otimes \mu^*)\mu^* = 0$, that is, $\forall x, y, z, u, v \in L$ and $\xi, \eta, \zeta, \alpha, \beta \in L^*$,

$$\begin{aligned} & \langle (1 - \omega_1 - \omega_2 - \omega_3)(1 \otimes 1 \otimes \mu^*)\mu^*(\xi), x \otimes y \otimes z \otimes u \otimes v \rangle \\ &= \langle (1 \otimes 1 \otimes \mu^*)\mu^*(\xi), (1 - \omega_1 - \omega_2 - \omega_3)(x \otimes y \otimes z \otimes u \otimes v) \rangle \\ &= \langle \mu^*(\xi), (1 \otimes 1 \otimes \mu)(1 - \omega_1 - \omega_2 - \omega_3)(x \otimes y \otimes z \otimes u \otimes v) \rangle \\ &= \langle \xi, \mu(1 \otimes 1 \otimes \mu)(1 - \omega_1 - \omega_2 - \omega_3)(x \otimes y \otimes z \otimes u \otimes v) \rangle. \end{aligned}$$

A 3-Lie coalgebra (L, Δ) [4] is a vector space L with a linear map $\Delta : L \rightarrow L \otimes L \otimes L$ satisfying $\text{Im}(\Delta) \subset L \wedge L \wedge L$, and $(1 - \omega_1 - \omega_2 - \omega_3)(1 \otimes 1 \otimes \Delta)\Delta = 0$, where $\omega_1, \omega_2, \omega_3 : L^{\otimes 5} \rightarrow L^{\otimes 5}$ satisfy identities (1), (2) and (3), respectively, and 1 is the identity of $L^{\otimes 5}$.

Let L^* be the dual space of L , e^1, \dots, e^m be the dual basis of e_1, \dots, e_m , that is, $\langle e^i, e_j \rangle = \delta_{ij}$, $1 \leq i, j \leq m$. Let $\mu^* : L^* \rightarrow L^* \otimes L^* \otimes L^*$ be the dual map of μ , for every $\xi \in L^*$, $x, y, z \in L$, $\langle \mu^*(\xi), x \otimes y \otimes z \rangle = \langle \xi, \mu(x, y, z) \rangle$.

Then we have the following result.

Lemma 2.1 [4] *Let L be a vector space over F , and $\mu : L \otimes L \otimes L \rightarrow L$ be a 3-ary linear map. Then (L, μ) is a 3-Lie algebra if and only if (L^*, μ^*) is a 3-Lie coalgebra with $\mu^* : L^* \rightarrow L^* \otimes L^* \otimes L^*$.*

Let (L_1, Δ_1) and (L_2, Δ_2) be 3-Lie coalgebras. If there is a linear isomorphism $\varphi : L_1 \rightarrow L_2$ satisfying $(\varphi \otimes \varphi \otimes \varphi)(\Delta_1(e)) = \Delta_2(\varphi(e))$, for all $e \in L_1$, then (L_1, Δ_1) is isomorphic to (L_2, Δ_2) , and φ is called a 3-Lie coalgebra isomorphism, where $(\varphi \otimes \varphi \otimes \varphi) \sum_i (a_i \otimes b_i \otimes c_i) = \sum_i \varphi(a_i) \otimes \varphi(b_i) \otimes \varphi(c_i)$.

Lemma 2.2 [4] *Let (L_1, Δ_1) and (L_2, Δ_2) be 3-Lie coalgebras. Then $\varphi : L_1 \rightarrow L_2$ is a 3-Lie coalgebra isomorphism if and only if the dual map $\varphi^* :$*

$L_2^* \rightarrow L_1^*$ is a 3-Lie algebra isomorphism from (L_2^*, Δ_2^*) to (L_1^*, Δ_1^*) , where for every $\xi \in L_2^*, v \in L_1, \langle \varphi^*(\xi), v \rangle = \langle \xi, \varphi(v) \rangle$.

A 3-Lie bialgebra[4] is a triple (L, μ, Δ) such that

- (1) (L, μ) is a 3-Lie algebra with the multiplication $\mu : L \wedge L \wedge L \rightarrow L$,
- (2) (L, Δ) is a 3-Lie coalgebra with $\Delta : L \rightarrow L \wedge L \wedge L$,
- (3) Δ and μ satisfy the following identity

$$\Delta\mu(x, y, z) = ad_\mu^{(3)}(x, y)\Delta(z) + ad_\mu^{(3)}(y, z)\Delta(x) + ad_\mu^{(3)}(z, x)\Delta(y),$$

where $ad_\mu(x, y) : L \wedge L \rightarrow End(L), ad_\mu(x, y)(z) = \mu(x, y, z)$ for $x, y, z \in L$, $ad_\mu^{(3)}(x, y), ad_\mu^{(3)}(z, x), ad_\mu^{(3)}(y, z) : L \otimes L \otimes L \rightarrow L \otimes L \otimes L$ are 3-ary linear maps satisfying for $u, v, w \in L$

$$\begin{aligned} & ad_\mu^{(3)}(x, y)(u \otimes v \otimes w) = (ad_\mu(x, y) \otimes 1 \otimes 1)(u \otimes v \otimes w) \\ & + (1 \otimes ad_\mu(x, y) \otimes 1)(u \otimes v \otimes w) + (1 \otimes 1 \otimes ad_\mu(x, y))(u \otimes v \otimes w) \\ & = \mu(x, y, u) \otimes v \otimes w + u \otimes \mu(x, y, v) \otimes w + u \otimes v \otimes \mu(x, y, w), \end{aligned}$$

and similar for $ad_\mu^{(3)}(z, x)$ and $ad_\mu^{(3)}(y, z)$.

Two 3-Lie bialgebras (L_1, μ_1, Δ_1) and (L_2, μ_2, Δ_2) are called *equivalent* if there exists a linear isomorphism $f : L_1 \rightarrow L_2$ such that

- (1) $f : (L_1, \mu_1) \rightarrow (L_2, \mu_2)$ is a 3-Lie algebra isomorphism, that is, $f\mu_1(x, y, z) = \mu_2(f(x), f(y), f(z))$ for $\forall x, y, z \in L_1$;
- (2) $f : (L_1, \Delta_1) \rightarrow (L_2, \Delta_2)$ is a 3-Lie coalgebra isomorphism, that is, $\Delta_2(f(x)) = (f \otimes f \otimes f)\Delta_1(x)$ for every $x \in L_1$.

3 The classification of 3-Lie coalgebras and 3-Lie bialgebras

We first give the following lemma.

Lemma 3.1[5] *Let (L, μ) be a 4-dimensional 3-Lie algebra with $\dim L^1 = 1$, and e_1, e_2, e_3, e_4 be a basis of L . Then L is isomorphic to one and only one of the two 3-Lie algebras $L_{b_1} = (L, \mu_{b_1})$ and $L_{b_2} = (L, \mu_{b_2})$, where*

$$L_{b_1} : \mu_{b_1}(e_2, e_3, e_4) = e_1; \quad L_{b_2} : \mu_{b_2}(e_1, e_2, e_3) = e_1.$$

Theorem 3.2 *Let (L, Δ) be a 4-dimensional 3-Lie coalgebra with $\dim L^1 = 1$, and e^1, e^2, e^3, e^4 be a basis of L . Then (L, Δ) is isomorphic to one and only one of the two 3-Lie coalgebras $C_{b_1} = (L, \Delta_{b_1})$ and $C_{b_2} = (L, \Delta_{b_2})$, where*

$$\Delta_{b_1}(e^1) = e^2 \wedge e^3 \wedge e^4; \quad \Delta_{b_2}(e^1) = e^1 \wedge e^2 \wedge e^3.$$

Proof The result follows from Lemma 2.1 and 2.2 and a direct computation, we omit the consideration process.

For a given 3-Lie algebra L , in order to find all the 3-Lie bialgebra structures on L , we should find all the 3-Lie coalgebra structures on L which are compatible with the 3-Lie algebra L . Although a permutation of a basis vectors of L gives isomorphic 3-Lie coalgebra structures, it may lead to the non-equivalent 3-Lie bialgebra structures on L . In the following, for a 3-Lie bialgebra (L, μ, Δ) , if the 3-Lie algebra (L, μ) is the case (L, μ_{b_i}) in Lemma 3.1 and the 3-Lie coalgebra (L, Δ) is the case (L, Δ_{b_j}) in Theorem 3.2, then we denote $(L, \mu_{b_i}, \Delta_{b_j})$ by $(L_{b_i}, C_{b_j}, \Delta_{b_k})$ or simply,

by (L_{b_i}, C_{b_j}) . The 3-Lie bialgebras (L_{b_i}, C_{b_j}) for $1 \leq i, j \leq 2$ are called the 3-Lie bialgebras of type (L_b, C_b) .

Theorem 3.3 The non-equivalent 4-dimensional 3-Lie bialgebras of type (L_b, C_b) are only as follows, for a basis e_1, e_2, e_3, e_4 of L ,

$$\begin{aligned} (L_{b_1}, C_{b_1}, \Delta_1): \Delta_1(e_2) &= e_1 \wedge e_3 \wedge e_4; & (L_{b_2}, C_{b_1}, \Delta_2): \Delta_1(e_2) &= e_1 \wedge e_4 \wedge e_3; \\ (L_{b_1}, C_{b_2}, \Delta_3): \Delta_3(e_2) &= e_2 \wedge e_1 \wedge e_3; & (L_{b_2}, C_{b_2}, \Delta_4): \Delta_4(e_1) &= e_1 \wedge e_2 \wedge e_4; \\ (L_{b_2}, C_{b_2}, \Delta_5): \Delta_5(e_1) &= e_1 \wedge e_2 \wedge e_3; & (L_{b_2}, C_{b_2}, \Delta_3): \Delta_3(e_2) &= e_2 \wedge e_1 \wedge e_3; \\ (L_{b_2}, C_{b_2}, \Delta_6): \Delta_6(e_2) &= e_2 \wedge e_1 \wedge e_4. \end{aligned}$$

Proof From Lemma 3.1 and Theorem 3.2 we need to verify that whether the following eight 3-Lie coalgebras of type C_{b_1} , which are obtained by permuting the basis vectors e_1, e_2, e_3, e_4 , are compatible with the 3-Lie algebra L_{b_1}

- (1) $\Delta(e_1) = e_2 \wedge e_3 \wedge e_4, \Delta(e_2) = \Delta(e_3) = \Delta(e_4) = 0;$
- (2) $\Delta(e_1) = e_2 \wedge e_4 \wedge e_3, \Delta(e_2) = \Delta(e_3) = \Delta(e_4) = 0;$
- (3) $\Delta(e_2) = e_1 \wedge e_4 \wedge e_3, \Delta(e_1) = \Delta(e_3) = \Delta(e_4) = 0;$
- (4) $\Delta(e_2) = e_1 \wedge e_3 \wedge e_4, \Delta(e_1) = \Delta(e_3) = \Delta(e_4) = 0;$
- (5) $\Delta(e_3) = e_1 \wedge e_2 \wedge e_4, \Delta(e_1) = \Delta(e_2) = \Delta(e_4) = 0;$
- (6) $\Delta(e_3) = e_1 \wedge e_4 \wedge e_2, \Delta(e_1) = \Delta(e_2) = \Delta(e_4) = 0;$
- (7) $\Delta(e_4) = e_1 \wedge e_2 \wedge e_3, \Delta(e_1) = \Delta(e_2) = \Delta(e_3) = 0;$
- (8) $\Delta(e_4) = e_2 \wedge e_1 \wedge e_3, \Delta(e_1) = \Delta(e_2) = \Delta(e_3) = 0.$

First we discuss the case (1). Thanks to Lemma 3.1, $\Delta\mu_{b_1}(e_1, e_2, e_3) = 0$. But $ad_{\mu_{b_1}}^{(3)}(e_1, e_2)\Delta(e_3) + ad_{\mu_{b_1}}^{(3)}(e_3, e_1)\Delta(e_2) + ad_{\mu_{b_1}}^{(3)}(e_2, e_3)\Delta(e_1) = \mu_{b_1}(e_2, e_3, e_2) \wedge e_3 \wedge e_4 + e_2 \wedge \mu_{b_1}(e_2, e_3, e_3) \wedge e_4 + e_2 \wedge e_3 \wedge \mu_{b_1}(e_2, e_3, e_4) = e_2 \wedge e_3 \wedge e_1 \neq 0$, that is,

$$\Delta\mu_{b_1}(e_1, e_2, e_3) \neq ad_{\mu_{b_1}}^{(3)}(e_1, e_2)\Delta(e_3) + ad_{\mu_{b_1}}^{(3)}(e_3, e_1)\Delta(e_2) + ad_{\mu_{b_1}}^{(3)}(e_2, e_3)\Delta(e_1).$$

Therefore, 3-Lie algebra L_{b_1} is not compatible with the case (1).

By the similar discussions to the case (1), the 3-Lie algebra L_{b_1} is not compatible with the case (2), and the 3-Lie algebra L_{b_2} is not compatible with the cases (1) and (2). And the 3-Lie algebras L_{b_1} and L_{b_2} are compatible with all the cases (3)-(8), respectively.

By the following 3-Lie bialgebra isomorphisms $f: L \rightarrow L$, in the case (L_{b_1}, C_{b_1}) :

- (4) \rightarrow (6), (3) \rightarrow (5): $f(e_1) = -e_1, f(e_2) = e_3, f(e_3) = e_2, f(e_4) = e_4;$
- (5) \rightarrow (8), (6) \rightarrow (7): $f(e_1) = -e_1, f(e_2) = e_2, f(e_3) = e_4, f(e_4) = e_3.$

In the case (L_{b_2}, C_{b_1}) :

- (4) \rightarrow (6), (3) \rightarrow (5): $f(e_1) = e_1, f(e_2) = e_3, f(e_3) = -e_2, f(e_4) = e_4;$
- (3) \rightarrow (4), (7) \rightarrow (8): $f(e_1) = -e_1, f(e_2) = e_2, f(e_3) = e_3, f(e_4) = e_4,$

and e_4 is in the center of the 3-Lie algebra $L_{\mu_{b_2}}$, we get the non-equivalent 3-Lie bialgebras of the types $(L_{b_1}, C_{b_1}, \Delta_1), (L_{b_2}, C_{b_1}, \Delta_2)$.

Second, we verify that whether the following twenty-four isomorphic 3-Lie coalgebras of the type C_{b_2} are compatible with the 3-Lie algebra L_{b_1} and L_{b_2} , respectively,

- (1) $\Delta e_1 = e_1 \wedge e_2 \wedge e_3, \Delta e_i = 0, i = 2, 3, 4;$ (2) $\Delta e_1 = e_1 \wedge e_2 \wedge e_4, \Delta e_i = 0, i = 2, 3, 4;$
- (3) $\Delta e_1 = e_1 \wedge e_3 \wedge e_4, \Delta e_i = 0, i = 2, 3, 4;$ (4) $\Delta e_1 = e_1 \wedge e_3 \wedge e_2, \Delta e_i = 0, i = 2, 3, 4;$
- (5) $\Delta e_1 = e_1 \wedge e_4 \wedge e_2, \Delta e_i = 0, i = 2, 3, 4;$ (6) $\Delta e_1 = e_1 \wedge e_4 \wedge e_3, \Delta e_i = 0, i = 2, 3, 4;$
- (7) $\Delta e_2 = e_2 \wedge e_1 \wedge e_3, \Delta e_i = 0, i = 1, 3, 4;$ (8) $\Delta e_2 = e_2 \wedge e_1 \wedge e_4, \Delta e_i = 0, i = 1, 3, 4;$

(9) $\Delta e_2 = e_2 \wedge e_3 \wedge e_4, \Delta e_i = 0, i = 1, 3, 4$; (10) $\Delta e_2 = e_2 \wedge e_3 \wedge e_1, \Delta e_i = 0, i = 1, 3, 4$;
 (11) $\Delta e_2 = e_2 \wedge e_4 \wedge e_1, \Delta e_i = 0, i = 1, 3, 4$; (12) $\Delta e_2 = e_2 \wedge e_4 \wedge e_3, \Delta e_i = 0, i = 1, 3, 4$;
 (13) $\Delta e_3 = e_3 \wedge e_1 \wedge e_2, \Delta e_i = 0, i = 1, 2, 4$; (14) $\Delta e_3 = e_3 \wedge e_1 \wedge e_4, \Delta e_i = 0, i = 1, 2, 4$;
 (15) $\Delta e_3 = e_3 \wedge e_2 \wedge e_4, \Delta e_i = 0, i = 1, 2, 4$; (16) $\Delta e_3 = e_3 \wedge e_2 \wedge e_1, \Delta e_i = 0, i = 1, 2, 4$;
 (17) $\Delta e_3 = e_3 \wedge e_4 \wedge e_1, \Delta e_i = 0, i = 1, 2, 4$; (18) $\Delta e_3 = e_3 \wedge e_4 \wedge e_2, \Delta e_i = 0, i = 1, 2, 4$;
 (19) $\Delta e_4 = e_4 \wedge e_1 \wedge e_2, \Delta e_i = 0, i = 1, 2, 3$; (20) $\Delta e_4 = e_4 \wedge e_1 \wedge e_3, \Delta e_i = 0, i = 1, 2, 3$;
 (21) $\Delta e_4 = e_4 \wedge e_2 \wedge e_3, \Delta e_i = 0, i = 1, 2, 3$; (22) $\Delta e_4 = e_4 \wedge e_2 \wedge e_1, \Delta e_i = 0, i = 1, 2, 3$;
 (23) $\Delta e_4 = e_4 \wedge e_3 \wedge e_1, \Delta e_i = 0, i = 1, 2, 3$; (24) $\Delta e_4 = e_4 \wedge e_3 \wedge e_2, \Delta e_i = 0, i = 1, 2, 3$.

By the similar discussions to the casae C_{b_1} , the only the cases (7), (8), (10), (11), (13), (14), (16), (17), (19), (20), (22) and (23) are compatible with L_{b_1} . And the only cases (9), (12), (15), (18), (19), (20), (21), (22), (23) and (24) are not compatible with the 3-Lie algebra L_{b_2} . By the following 3-Lie bialgebra isomorphisms $f : L \rightarrow L$,

in the case $(L_{b_1}, C_{b_2}) : (8) \rightarrow (22) : (e_1) = -e_1, f(e_2) = e_4, f(e_3) = e_3, f(e_4) = e_2$;
 (7) $\rightarrow (8), (10) \rightarrow (11) : f(e_1) = e_1, f(e_2) = -e_2, f(e_3) = e_4, f(e_4) = e_3$;
 (13) $\rightarrow (14), (16) \rightarrow (17) : f(e_1) = e_1, f(e_2) = e_4, f(e_3) = -e_3, f(e_4) = e_2$;
 (19) $\rightarrow (20), (22) \rightarrow (23) : f(e_1) = e_1, f(e_2) = e_3, f(e_3) = e_2, f(e_4) = -e_4$;
 (7) $\rightarrow (10) : f(e_1) = -e_1, f(e_2) = -e_2, f(e_3) = e_3, f(e_4) = e_4$;
 (7) $\rightarrow (13) : f(e_1) = -e_1, f(e_2) = e_3, f(e_3) = -e_2, f(e_4) = -e_4$;
 (7) $\rightarrow (16) : f(e_1) = -e_1, f(e_2) = e_3, f(e_3) = e_2, f(e_4) = e_4$;
 (8) $\rightarrow (19) : f(e_1) = -e_1, f(e_2) = e_4, f(e_3) = -e_3, f(e_4) = -e_2$.

$(L_{b_2}, C_{b_2}) : (1) \rightarrow (4), (2) \rightarrow (5), (3) \rightarrow (6), (7) \rightarrow (10), (8) \rightarrow (11), (13) \rightarrow (16), (14) \rightarrow (17) : f(e_1) = -e_1, f(e_2) = e_2, f(e_3) = e_3, f(e_4) = e_4$;
 (2) $\rightarrow (3) : f(e_1) = -e_1, f(e_2) = e_3, f(e_3) = -e_2, f(e_4) = -e_4$;
 (7) $\rightarrow (13), (8) \rightarrow (14) : f(e_1) = e_1, f(e_2) = -e_3, f(e_3) = e_2, f(e_4) = e_4$,
 and e_4 is in the center of the 3-Lie algebra L_{b_2} , we obtain the result.

Acknowledgements

The first author (R.-P. Bai) was supported in part by the Natural Science Foundation (11371245) and the Natural Science Foundation of Hebei Province (A2014201006).

References

- [1] W. Michaelis, Lie coalgebra, *Adv. Math*, 38 (1980):1-54.
- [2] A. Bolavin, V.G. Drinfeld, Solutions of the classical Yang- Baxter equation for simple Lie algebras, *Func. Anal. Appl*, 16 (1982):159-180.
- [3] V. DeSmedt, Existence of a Lie bialgebra structure on every Lie algebra, *Lett. Math. Phys*, 31(1994): 225-231.
- [4] R. Bai, Y. Cheng, J. Li, W. Meng, 3-Lie bialgebras, *Acta Math. Scientia*, 2014, 34B(2):513-522.
- [5] V. Filippov, n -Lie algebras, *Sib. Mat. Zh.*, 26 (1985) 126-140.