

# An Introduction on Weakly TR-Contraction in Metric Spaces

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## Abstract

In this paper , we introduce the concepts of weakly TR-contraction in metric spaces . Then we prove some results.

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## 1 Introduction

Contractions are one of the important class of mappings .Many of authors have studied fixed, periodic and coincide points of them . Recently , A . Beiranvand , S . Moradi , M . omid and H . Pazandeh [1] introduced a new class of contractive mappings :T-contraction and T-contractive extending the Banach's contraction principle and the Edeistein's fixed point theorems (*see [2]*), respectively . Authors in [3] considered various extensions of classic contraction type of mappings [more specifically : Kannan , Zanghirescu , weak contraction and also the so-called  $D(a, b)$  class] . For these classes of contractions , conditions for existence and uniqueness of fixed points , as well for its asymptotic behavior is given [1,4,5] . The goal of this paper is to introduce the new class of contractions in metric spaces .

First, we have the following definitions and results.

**Definition 1.1.** Let  $(X, d)$  be a metric space. A map is said to be a contraction when there exists  $0 \leq \alpha < 1$  so that

$$d(Sx, Sy) \leq \alpha d(x, y)$$

**Theorem 1.2 (Banach's contraction principle) [6].** Let  $(X, d)$  be a complete space and  $T : X \rightarrow X$  a contraction. Then  $T$  has a unique fixed point.

**Definition 1.3 [7].** Let  $(X, d)$  be a metric space and  $S, T, R : X \rightarrow X$  three functions. A mapping  $S$  is said to be a TR-contraction if there is  $\alpha \in [0, 1)$  constant such that

$$d(TSx, RSy) \leq \alpha d(Tx, Ty)$$

For all  $x, y \in X$ .

**Example 1.4.** Let  $X = \mathbb{R}$  with usual metric. We consider the functions  $S, T, R : X \rightarrow X$  defined by  $Tx = \frac{x}{2}$ ,  $Rx = \frac{x}{8}$  and  $Sx = \frac{x}{4}$ . If  $\alpha \in \left[\frac{1}{4}, 1\right)$ , then  $S$  is a TR-contraction.

**Notation 1.5.** In this paper, the space of all linear bounded mappings on a normed space  $X$  is denoted by  $BL(X)$ . It is a normed space with the following norm:

$$\|T\| = \{\sup\|Tx\| : x \in X, \|x\| = 1\}$$

## 2 Main Results

Throughout this section,  $X$  denotes a metric space.

**Definition 2.1.** Let  $(X, d)$  be a metric space and  $S, T, R : X \rightarrow X$  three functions. A mapping  $S$  is said to be a weakly TR-contraction if there are  $\alpha, \beta \in [0, 1)$  with  $0 \leq \alpha + \beta < 1$  such that

$$d(TSx, RSy) \leq \alpha d(x, y) + \beta d(Tx, Ry)$$

For all.

**Remark 2.2.** Clearly, any TR-contraction is weakly TR-contraction but the converse need not be hold; for example, consider  $X = [0, \infty)$  with usual metric and  $S, T, R : X \rightarrow X$  by  $Tx = x^2$ ,  $Rx = x$  and  $Sx = \sqrt{x}$ .

Set  $x = \frac{1}{2}$  and  $y = 0$ , then we have

$$|x - \sqrt{y}| = d(TSx, RSy) \xrightarrow{x=\frac{1}{2}, y=0} d\left(TS\left(\frac{1}{2}\right), RS(0)\right) = \frac{1}{2}$$

And

$$|x^2 - \sqrt{y}| = d(Tx, Ry) \xrightarrow{x=\frac{1}{2}, y=0} d\left(T\left(\frac{1}{2}\right), R(0)\right) = \frac{1}{4}$$

Which  $d\left(TS\left(\frac{1}{2}\right), RS(0)\right) > d\left(T\left(\frac{1}{2}\right), R(0)\right)$ . Hence  $S$  is not a TR-contraction. It is easy to show that  $S$  is a weakly TR-contraction.

**Theorem 2.3.** Let  $S : X \rightarrow X$  be a weakly TR-contraction. Also, suppose that  $X$  be complete. Further, Let  $T$  be a contraction. Then  $T$  and  $R$  have a coincide point.

**Proof.** By Banach's contraction principle,  $T$  has an unique fixed point, say  $x^*$ .

Now, set  $x = y = x^*$  in [2.1.1]. Then we have

$$d(TSx^*, RSx^*) \leq \alpha d(x^*, x^*) + \beta d(Tx^*, Rx^*)$$

Which implies  $d(Tx^*, Rx^*) = 0$ . Since  $0 \leq \beta < 1$ , so  $d(Tx^*, Rx^*) = 0$  which means  $x^* = Rx^*$ . This completes the proof.

**Definition 2.4.** Let  $S, T : X \rightarrow X$ . We say that  $S$  is T-contraction if there is a  $\alpha \in [0, 1)$  such that

$$d(TSx, TSy) \leq \alpha d(Tx, Ty)$$

For all  $x, y \in X$ .

**Remark 2.5.** Indeed, the previous definition is the concept of a TR-contraction in which  $R = T$ .

**Definition 2 .6 .[8]** Let  $S : X \rightarrow X$  be a mapping . We say that  $S$  is sequentially contraction , if there exist a sequence as  $(T_n) : X \rightarrow X$  such that  $S$  be a  $T_n$  – contraction for each  $n$  .

**Example 2 .7.** Consider  $X = [1, \infty)$  with usual metric. Also, let  $S, T_n : X \rightarrow X$  by  $Sx = \sqrt{x}$  and  $T_n x = \frac{x^2}{n}$  for all  $n \in \mathbf{N}$  . Then

$$d(T_n Sx, T_n Sy) = \frac{1}{n} |x - y|$$

And

$$d(T_n x, T_n y) = \frac{1}{n} |x - y| |x + y|$$

So ,  $S$  is sequentially contraction .

Finally we prove the following result.

**Theorem 2 .8.** Let  $X$  be a normed space and  $S : X \rightarrow X$  a mapping. Suppose that there exists  $T \in BL(X)$  such that  $S$  be a  $T$  –contraction. Then  $S$  is sequentially contraction.

**Proof.**  $BL(X)$  is closed with sup-norm . Hence there exists a sequence, say  $(T_n)$ , such that  $T_n \rightarrow T$  as  $n \rightarrow \infty$  . On the other hand,  $S$  is  $T$ -contraction, i .e,

$$d(TSx, TSy) \leq \alpha d(Tx, Ty)$$

For some  $0 \leq \alpha < 1$  . We have

$$d\left(\lim_{n \rightarrow \infty} T_n Sx, \lim_{n \rightarrow \infty} T_n Sy\right) \leq \alpha d\left(\lim_{n \rightarrow \infty} T_n x, \lim_{n \rightarrow \infty} T_n y\right)$$

So

$$\lim_{n \rightarrow \infty} d(T_n Sx, T_n Sy) \leq \alpha \lim_{n \rightarrow \infty} d(T_n x, T_n y)$$

Therefore , We can choose  $N \in \mathbf{N}$  so that

$$d(T_n Sx, T_n Sy) \leq \alpha d(T_n x, T_n y)$$

For all .Set  $\tilde{T}_n = T_{n+(N-1)}$  for each . Obviously , is  $\tilde{T}_n$ -contraction for all  $n$  , as desired .

## References

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